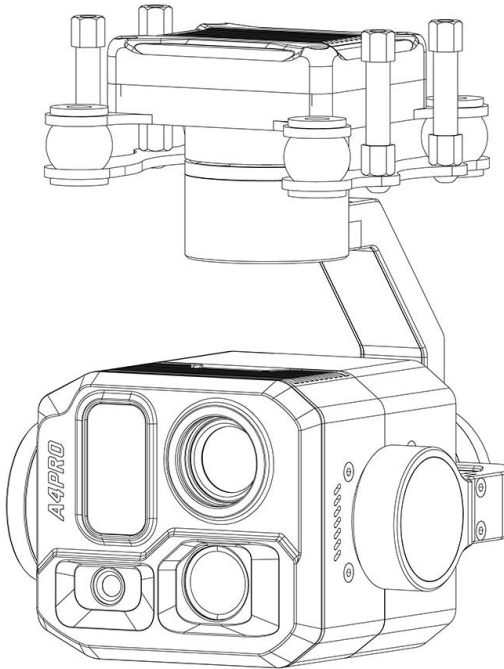


INYYO A4PRO

User Manual

V1.0

2025/1/15



Understanding the product usage safety is of great importance for the safety of yourself, people around you and the environment. Please be sure to read the *User Manual* carefully. The individual parameters of this type of product are updated and upgraded rapidly, so please refer to the latest version V1.0. The final interpretation right of this document and all related documents belongs to the developer of this product.

Keyword Search

Electronic documents can use the search function to search for keywords. In common office software, Windows users can use the shortcut key Ctrl+F, Mac users can use Command+F to search for keywords.

Click on the directory subtitle to jump

Users can click the subtitle in the directory to jump to the corresponding pages.

Printing

This document supports low/medium/high quality printing.

Reading Tips

Symbol Explanations

 **Prohibition**  **Key Attention or Warning**  **Reminder**  **Note**

Disclaimer

·Neither this product nor its developer/manufacturer/distributor shall be liable for any damage, injury, or legal liability directly or indirectly caused by the use of this product. Users shall comply with all safety guidelines including but not limited to those mentioned in this document.

·This product is originally designed solely for legal civil applications and not for military purposes. Any activities conducted by users using this product are their personal behaviors and have no connection with the product's developer, manufacturer, or distributor.

·Due to the relatively fast update and replacement cycle of products in this category, slight deviations between the final physical product and the technical parameters are considered normal.

·The final interpretation right of this document and all related documents belongs to the developer of this product. For any updates, no separate notice will be given.

Important Notes

- Please read this manual carefully before using the product and operate it strictly in accordance with the manual.
- Do not attempt to disassemble, modify, or repair the product by yourself. If necessary, please contact the distributor.

- For after-sales service, please contact the distributor. For details, refer to the relevant after-sales service content in this document.

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Product Introduction

This chapter mainly introduces the functional features, technical specifications, component names of the main core modules of this product, and general precautions for using this product.

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Product Introduction

Overview

- The action camera specially customized for INYYO A4Pro has 8K visible light resolution and 48 million pixels. It adopts a unique motion vision focusing algorithm and real-time HDR processing technology, which can maintain accurate focusing during high-speed movement and collect and restore natural and vivid colors of different scenes.
- Made of aviation aluminum alloy through CNC precision machining, it has high strength and fast heat dissipation. It can start and work in the temperature range of $-20^{\circ}\text{C} \sim 60^{\circ}\text{C}$, and has good vibration absorption, rain resistance, dust resistance and corrosion resistance, which can adapt to harsh field working environments.
- The advanced three-axis orthogonal stabilized gimbal works closely with the mounting platform. The high-speed processor controls the precise operation of the motor, which has a high steady-state frequency and compensates for every slight movement, so that the camera maintains a stable shooting angle.
- The 13.5mm focal length uncooled infrared thermal imaging camera can easily detect the target details at a longer distance, supports thermal image switching, and provides black-hot, white-hot and color palettes. You can adjust the color according to the scene to obtain a more recognizable thermal imaging image.
- Adopting an advanced process AI chip with a built-in NPU computing capability of up to 10.0 Tops, it has the function of automatic detection and recognition of typical targets such as vehicles and people; it can detect multiple targets at the same time, and the target detection probability is better than 90%.
- The zoom lens can perform high-precision real-time detection and tracking or feature tracking of ground targets within the visible range. The tracking process can resist changes in light, target scale, occlusion, rotation, blur, deformation and fast movement; it has the functions of automatic zoom during tracking and automatic tracking based on target recognition results, making it easy to perform tasks such as reconnaissance and surveillance.
- The original 3D visual positioning system can real-time calculate the longitude and latitude coordinates, elevation information and distance information of the center point of the image, and transmit the real-time data back through the serial port and network port; it has good application value in long-distance reconnaissance, precise determination of control point coordinates, and

overview of visible areas.

- The integrated control module structure greatly enhances the connection strength, allowing you to enjoy a comfortable experience brought by the intelligent structure.
- The exterior of the control module is designed with all-metal material, which has better safety features such as high temperature resistance, corrosion resistance, vibration resistance, water resistance, electric shock resistance, anti-interference, long service life and not easy to loose. It can effectively prevent current leakage and short circuit, and ensure the reliability of electrical connection.
- The integrated control module has multiple optimized one-key functions, making the operation experience more comfortable.
- It can be compatible with various mechanical platforms, and multiple peripheral connection solutions allow you to use it without any restrictions.



Please refer to the technical index of this paper for the actual use environment and specific parameters.

Technical Specifications

Main Parameters	
Material	Aviation Aluminum Alloy
Pod Dimension	106.7 (L) × 92.5 (W) × 126.7 (H) mm
Pod Weight	480 ± 10 g
Operating Temperature	-20°C ~ 60°C
Storage Temperature	-30°C ~ 70°C
Protection Class	IP43
Image Stabilization Axes	3 Axes (Yaw/Pitch/Roll)
Angular Operating Range	-160° ~ 160° (Yaw); -120° ~ 30° (Pitch); ±40° (Roll)
Control Signal	S.BUS, TTL Serial Communication, TCP, UDP
Input Voltage	12V
Power	13W
Optical Zoom	11X
Hybrid Zoom	176X
Video Interface	Ethernet Port
PTZ Operating Modes	Follow Enabled (Default); Follow Disabled; One-Click Down
PTZ Control Modes	Speed Control; Angle Control; Point-and-Go; Target Tracking
Image Storage Format	JPG
Video Storage Format	MP4
Video Output Format	1920*1080@30fps
Supported Storage Capacity	Micro SD: 32GB (Minimum) / 512GB (Maximum)
Visible Light Zoom Module	
Focal Length	15 ~ 50 mm
Sensor	1/2" CMOS, Effective Pixels 48.0 MP
Zoom Control Modes	Speed Control, Magnification Control
Field of View (H×V×D)	W: 23.2°(H) 17.6°(V); T: 7.2°(H) 5.4°(V)
Visible Light Resolution	8000*6000@30fps

Manual Recognition Distance (Human)	1800 m
Manual Recognition Distance (Vehicle)	3700 m
AI Recognition Distance (Human)	2200 m
AI Recognition Distance (Vehicle)	2600 m
Visible Light Wide-Angle Module	
Sensor	1/2" CMOS
Effective Pixels	48.0 MP
Focal Length	4.5 mm (Equivalent Focal Length 24 mm)
Aperture	f/2.8
Field of View (H×V)	HFOV=83.4 ° ; VFOV during photo shooting is approximately 67.4 ° ; VFOV during video streaming is approximately 53.1°
Visible Light Resolution	8000*6000@30fps
Thermal Imaging Module	
Thermal Imaging Sensor	Vanadium Oxide Uncooled IR Focal Plane Array
Thermal Imaging Focal Length	13.5 mm
Field of View (Horizontal × Vertical)	31.9° × 25.7°
Thermal Imaging Resolution	640*512
Pixel Pitch	12 μm
Wavelength Range	8 ~ 14 μm
Thermal Sensitivity	≤ 40 mK @ 25°C, F#1.0
Digital Zoom	1 ~ 8x
Palette	Black-Hot / White-Hot / Color
Manual Recognition Distance (Human)	300 m
Manual Recognition Distance	1000 m

(Vehicle)	
AI Recognition Distance (Human)	400 m
AI Recognition Distance (Vehicle)	1500 m
Laser Ranging Module	
Ranging Range	5 - 1500 m
Ranging Modes	Continuous Ranging, Single Ranging
Ranging Accuracy	±1 m
AI Target Tracking Module	
Auto-Detected Target Types	Typical targets such as vehicles, personnel, etc.
Target Detection Rate	≥ 90%
Occlusion Resistance Time	1 second
Resistance to Target Deformation/Occlusion	Automatic
Target Switching & Tracking	Supported
Target Tracking Modes	Recognition Tracking, Feature Tracking
Target Selection Method for Tracking	Point-and-Track
Auto-Zoom During Tracking	Supported
Neural Network Computing Power	10.0 TOPS
Target Positioning	
Target Positioning Method	Image Center Point Positioning (Requires GPS Signal Reception)
Target Calculation Accuracy	≤ 10 m (Under Non-Complex Terrain Conditions)
Coordinate Output Type	Latitude and Longitude
Buck Converter Module	
Dimension	50.51 (Length) * 50.35(Width) * 20.77 (Height) mm
Weight	64.7±5g
Input Voltage	16-58V

Output Voltage	12 V
Connection Method	Connect the output terminal (XT30 connector) of the buck converter module to the control module (XT30 connector). Only independent power supply for the pod is permitted.

■ The **buck module** must be used to supply power to the gimbal independently; the **buck module** cannot supply power to other devices, nor can it supply power to the gimbal together with other devices.

■ Description of PTZ working mode

1. Enable follow (default mode): The yaw axis of PTZ moves in real time along the horizontal direction of the current attached equipment. After the horizontal rotation of the attached equipment, PTZ will slowly correct the position of the current yaw axis in real time for about 6s, and stop after confirming the complete reset.
2. Disable follow: Lock the plane position of the current PTZ yaw axis and no longer follow the horizontal direction of the current attached equipment. This mode have temperature drift is normal phenomenon, which is generally used for surround shooting.
3. One-click down: The pitch axis of the PTZ moved to -90°.It is used to collect orthophoto images. This function is prohibited for the upper PTZ.

■ Description of PTZ control mode

1. Speed control: Control the PTZ to move in a certain direction at an adjustable speed.
2. Angle control: Control the PTZ to rotate to a fixed angle, this function is limited to Instruction control.
3. Pointing movement: control the PTZ to rotate to the specified visual position based on the XY coordinates of the screen, this function is limited to Instruction control.
4. Target tracking: The automatic control PTZ stabilizes the selected target at the center point of the screen in real time. During the tracking process, the user cannot manually control it, and can exit the tracking mode after canceling the tracking.

■ Camera Zoom Control Mode Description

Magnification Control: Controls the optical zoom of the visible light camera to a specific fixed magnification. This function is only available via command control.

■ **The manual control speed can adaptively adjust with the zoom of the optical module, allowing users to obtain a smooth control experience when operating at high magnifications.**

■ **Target tracking mode description**

1. Recognition tracking: The PTZ performs high-precision automatic tracking based on the detection/recognition results of typical targets already supported by AI (typical target models are trained based on the aircraft's overhead view angle, and the detection rate cannot be guaranteed under other views), and can automatically zoom according to the size of the identified target.
2. Feature tracking: The PTZ performs image feature tracking based on the user's selected non-AI recognition target.

■ **Target location function description**

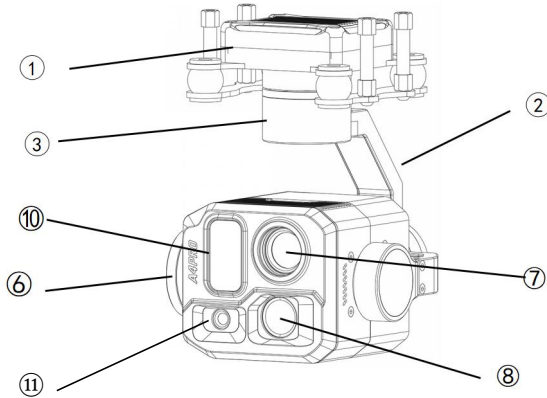
After entering the specified receiving protocol, the photoelectric pod will automatically locate the center point target on the screen (required to be used below the pitch axis of -30°), and output the latitude and longitude coordinates of the target in the reply data and OSD display.



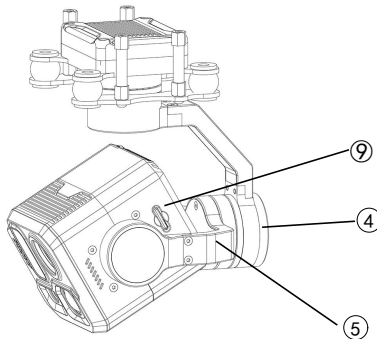
Due to the relatively fast update and replacement cycle of products in this category, slight deviations between the final physical product and the technical parameters are considered normal.

Main Part Description

■ Pod body:

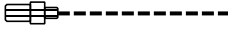
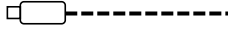


① Control Module	② Yaw Arm	③ Yaw Servo Motor
④ Roll Servo Motor	⑤ Roll Arm	⑥ Pitch Servo Motor
⑦ Thermal Imaging Module	⑧ Zoom Module	⑨ SD Card Slot
⑩ Laser	⑪ Wide-Angle Module	



Due to the relatively fast update and replacement cycle of products in this category, slight deviations between the final physical product and the technical parameters are considered normal.

Packing List

 <p>Pod Main Unit × 1</p>	 <p>Buck Converter Module × 1</p>	 <p>Power Cable × 1</p>  <p>Ethernet Cable × 1</p>  <p>USB-TTL Adapter × 1 + Dupont Wire × 1</p>
--	--	---

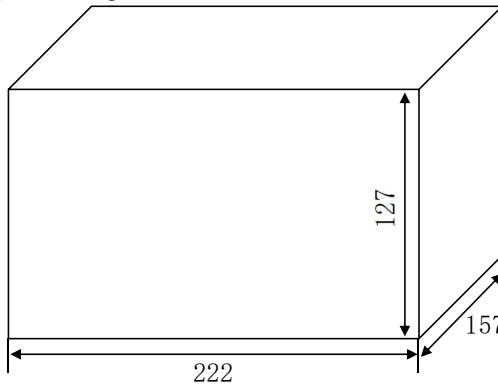
■ Example of Product Main Unit Packaging Box:

Packaging Box Type: Top-and-Bottom Box

Packaging Box Liner: Sponge Filled

Packaging Box Dimension: 222(Length) × 157(Width) × 127(Height) mm

Packaging Box Weight: 396± 20 g



·The pod main unit comes with a 32G memory card.

·Due to differences in users' operating environments and interface of mounting platforms, [please prepare other cables by yourself according to the electrical interface definitions in this document.](#)

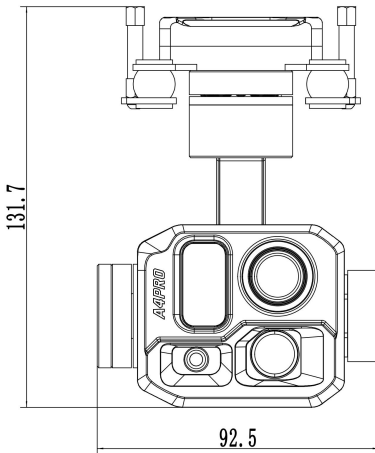
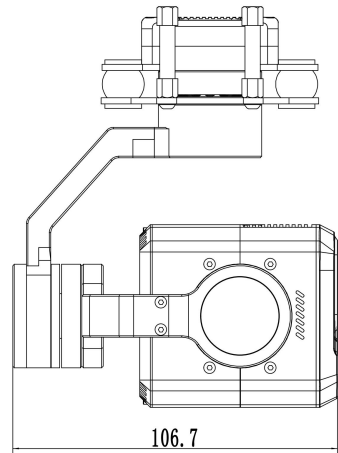
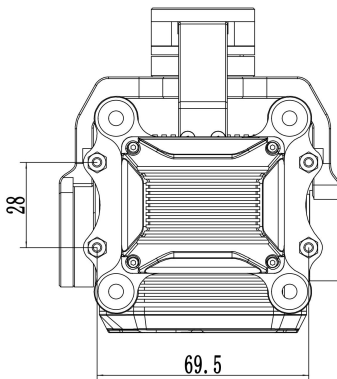
Thank you for your understanding!



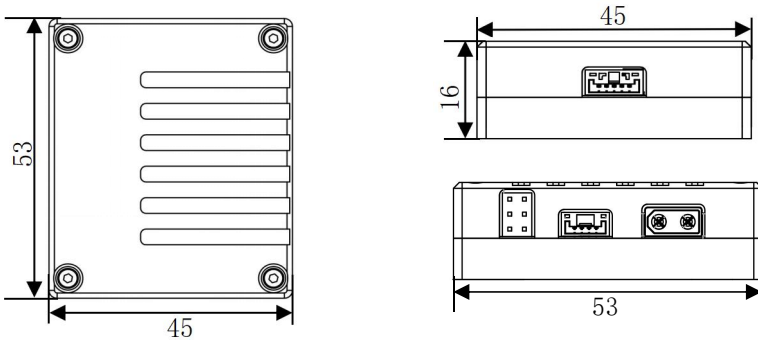
The above is the default packing list of this product. For other accessory requirements, please contact the distributor.

Mechanical Dimensions (Unit: mm)

■ Pod Main

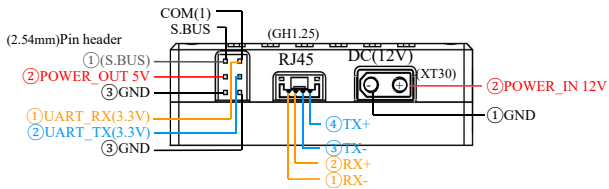


■ **12V Single Ethernet Port Output Control Module (Default):**



Interface Definition

■ **12V Single Ethernet Port Output Control Module (Default):**



Note

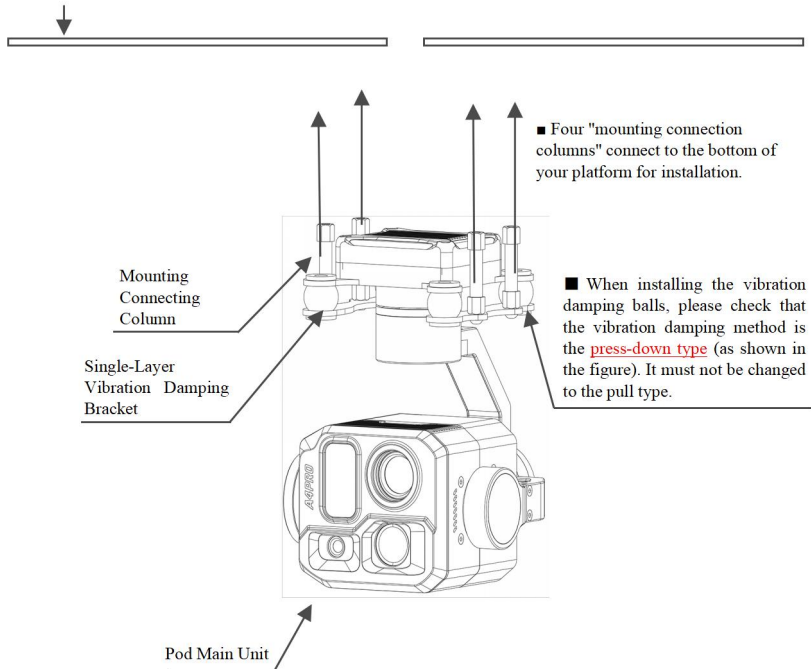
DC	Power interface. Do not input voltage beyond the supported range.
RJ45 Ethernet Port	Connect to image/data transmission device, used for video reading or TCP/UDP command control.
S.BUS	Connect to remote controller receiver, used for S.BUS joystick control.
COM(1) (UART Serial Port)	Connect to image/data transmission device or flight controller, used for serial port command control and data reading. Defaults to TTL.

The factory default 12V single-netport output control module is standard.

Installation Method

■ Control Module and Mounting Platform:

■ Schematic Diagram of the Application Platform Bottom:



Users need to drill holes on the application platform by themselves to install the electro-optical pod.

General Note

- Please confirm the **power supply voltage** in strict according to the electrical interface definition in this article. Do not input voltage beyond the supported range, otherwise the device will burn out;
- Before supplying power to the module, please **confirm the positive and negative poles of the power supply**;
- When using battery power, please check to **make sure the battery can supply power normally(12V)**;
- When you need to control the pod through serial port, please **do not input voltage through serial port**, otherwise it will damage control board;
- When installing the vibration damping balls, please **check whether the vibration damping mode is down pressure type**, and cannot be changed to pull type, otherwise it will cause serious consequences such as falling;
- Ensure that the PTZ remains free from obstacles at all times**. Obstructions within the PTZ operating range can impair normal functionality and may lead to serious repercussions, such as burning out the PTZ;
- Do not increase the hood, counterweight and other items**, otherwise the PTZ will be underperforming, and even result in burning and other serious consequences;
- Do not use thermal imaging equipment to photograph the sun, otherwise it will burn the heat sensor;
- Do not look directly at the laser beam in the backlight with your eyes or use an optical instrument to **observe the laser beam in the backlight. No flammable objects are blocked within 20cm** in front of the laser device;
- The quick-release interface **does not support hot swapping**;
- Do not remove the SD card during shooting or video recording**, otherwise the images obtained during the photo shooting may be lost;
- Please keep the lens clean and wipe it with a dust-free glasses cloth**. Too dirty lens will result in slow focusing speed and even cannot focus and other consequences;
- Do not disassemble or repair by yourself**, otherwise you will not be able to enjoy the warranty service.

Product Use

This chapter describes the channel definition, network port Settings, modifying IP addresses and coding configurations, and command protocols.

[> Click here to return to Table of contents <](#)

Product Use

S.BUS Channel description

Channel (Default)	Function
RC_CH1 – Pitch	Up - Up
	Mid - Standby
	Down - Low
RC_CH2 – Zoom	Up – Narrow
	Mid – Standby
	Down - Enlarge
RC_CH3 – Yaw	Left - Towards the left
	Mid - Standby
	Right - Towards the right
RC_CH4 – Mode switch, one-click down	Up – Disable follow
	Mid - Enable follow (Default mode)
	Down - One-click down
RC_CH5 – Photography	Up - Take a photo
	Down - Start / stop recording
RC_CH6– Target detection , Target tracking	Up – Target detection switch
	Down –Target tracking switch
RC_CH7 – One-click reset	Up - One-click reset
RC_CH8 – PIP, Pseudo-color switch	Up – black heat, white heat, color switch
	Down – Screen mode (PIP) switch
RC_CH9 – OSD switch	Up – OSD on
	Down – OSD off



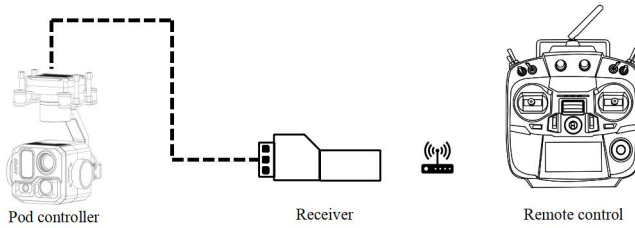
Up



Mid



Down



- Connect your receiver or other link transmission equipment to the S.BUS interface of the pod (conventional remote controls typically use a DuPont plug), and set up your remote control channels as needed;
- The rotation speed of PTZ is linear with the gear value, When the channel gear value is less than 50, PTZ will not act. It is normal that some remote controllers with lower accuracy cannot stop the movement of PTZ after the rocker returns to the center. When operating the rocker, the movement needs to slowly return to the center to avoid effectively.
- The camera can take pictures during recording.
- The pitch axis is self-stable, and the pitch angle relative to the plane position is maintained in real time.
- The working status of the yaw axis depends on the "Enable follow" and "Disable follow" modes.
- The horizontal roller is self-stabilizing and keeps the horizontal attitude in real time.

■ S.BUS channel setting instruction:

No.	Function	Byte	Note
1	Header	0xEE	
2	Message ID	0x82	
3	Frame length	0x1C	The length of all messages is 28 bytes
4	Pitch		The corresponding byte for each function represents the corresponding channel number, such as the pitch byte is 0x01, and the yaw byte is 0x03, which represent channel 1
5	Yaw		
6	Visible light zoom		
7	Visible light manual focus		
8	PTZ Mode switch, One-click down		
9	One-click reset		
10	Photography		

11	Target detection and tracking		controlling pitch and channel 3 controlling yaw. The channel number range is 1-16. If it exceeds the range, it cannot be set successfully, and "0" represents not activating this function.
12	PIP, black heat, white heat, color		
13	Thermography electronic zoom		
14	Laser ranging(none)		
15	Laser night vision (none)		
16	OSD-switch		
17	Reserve		
18	Reserve		
19	Reserve		
20	Reserve		
21	Reserve		
22	Reserve		
23	Reserve		
24	Reserve		
25	Reserve		
26	Reserve		
27	Reserve		
28	Sum check		1-27 byte sum, take the lower eight bits

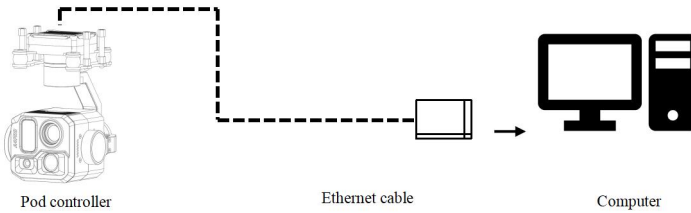
• Example:

```
0xEE,0x82,0x1C,0x01,0x03,0x02,0x04,0x05,0x06,0x00,0x00,0x00,0x00,0x00,0x00,0x00,
0x00,0x00,0x00,0x00,0x00,0x00,0x00,0x00,0x00,0x00,0x00,0xA1
```

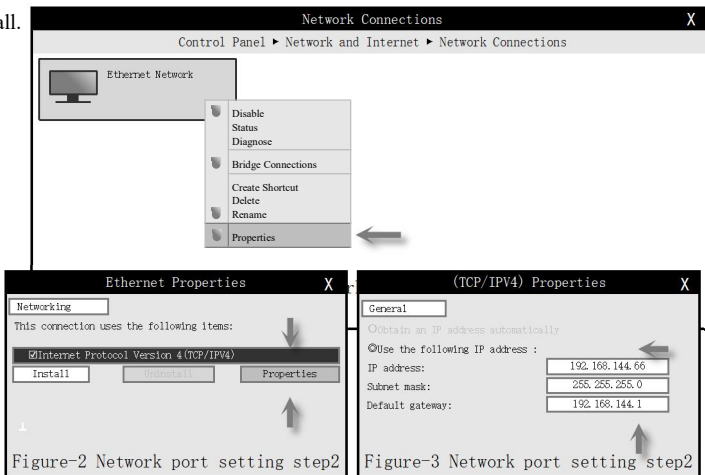
(Pitch is CH1, yaw is CH3, zoom is CH2, manual focus is CH4, mode switch is CH5, one click reset is CH6, and other functions are not mapped)。

To set the S.BUS channel, you need to connect the serial port. Send the setting instruction in the above format or use the software client to set it. The Baud of the serial port is [115200](#). To use the PC terminal for operation, you need to provide your own USB to TTL serial port module for connection.

Network Port Setting

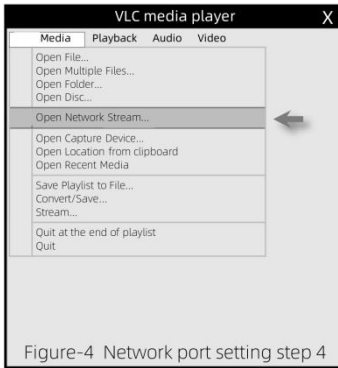
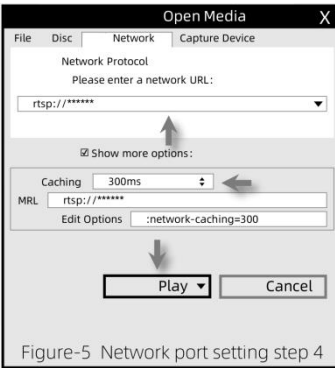


1. Take the PC as an example (you can flexibly connect other link devices based on your requirements), connect the cable to the network port of the PC, and disable the firewall.



2. Open the “network” on your computer, select the “network and Internet settings” then select the “change adapter option”, and finally select “IPv4” in “Ethernet” to modify the computer website. Please make sure that the computer and pod are in the same network segment, as shown in the figure.

3. After setting the network segment of the computer, enter the url (default) 192.168.144.119:8554 into the configuration interface, and you can set the video pull flow address, url, port number, compressed format (H.264/265) and bit rate.



4.Open VLC media player(Download software by yourself), Enter the pod RTSP video (default) address:

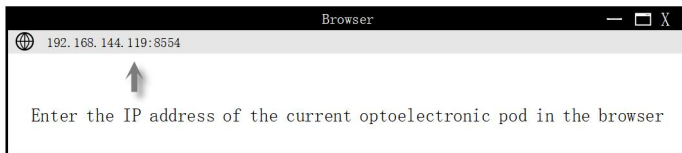
□ <rtsp://192.168.144.119/554>

“Caching” input “300ms” for better video effect.

5.TCP default control port: [2000](#)

■ Modify IP address and video encoder configuration:

①Power up the photoelectric pod normally, connect the network port to the computer, and log in to [192.168.144.119:8554](#) on the browser (192.168.144.119 is the current IP address of photoelectric pod) for coding configuration.



②Enter the coding configuration page, and the basic information on the configuration page is as follows:

- [System Information](#)
- [Soft Version](#)



Users need to remember the modified IP address, if you forget it, you can use "IPScan" to retrieve it.

Menu
[Home](#)
[Videos](#)
[Images](#)
[TF Devices](#)
[Settings](#)

System Information

Hardware Version
A1B0C1_37_001 2.0.0

Software Version
kernel: 4.19.90
rootfs: 2024.02.10-0-p98cc5a74c4+02050730140456
trackapp: 1.0.0-2902-p0a0276f+20230909160951

Network Configuration
IP Address:
Subnet Mask:
Gateway:
DNS Server:

System Actions

- **Home:** Main Page.
- **Hardware Version:** Hardware Version.
- **Software Version:** Software Version.
- **Network Configuration:** Network-related Settings.
- **IP Address:** The IP address of this product, default is 192.168.144.119, with the port number 2000. Users can modify this address freely (please do not forget it). This address must be in the same network segment as the IP address of your computer. If they are not in the same segment, you need to configure the Ethernet address on the computer you are using.
- **Subnet Mask:** Subnet Mask.
- **Gateway:** Gateway.
- **DNS Server:** DNS Server.
- **Save Network Settings:** Save Network Settings. After modifying the above four network settings, you need to click this button to save them. The page will display "Network settings updated successfully".
- **System Actions:** System Actions.
- **Restart System:** Restart System. After modifying the device configuration, restart the system to apply the changes.

Menu

- Home
- Videos
- Images
- TF Devices
- Settings

Settings

Video Codec Selection

☐ H264 ☒ H265

VENC Settings

Main VENC Bitrate (Kbps, max 20000): 2000 [Set Main Bitrate](#)

VIS VENC Bitrate (Kbps, max 81920): 81920 [Set VIS Bitrate](#)

IR VENC Bitrate (Kbps, max 20000): 16000 [Set IR Bitrate](#)

RTSP Stream Settings

Enable Multi-RTSP Streams: ☐

UDP Multicast Settings

UDP Stream: ☐

UDP Address: 192.168.1.121 [Set UDP Address](#)

UDP Port: 8666 [Set UDP Port](#)

Client Control Settings

Control Port: 2000 [Set Control Port](#)

Lens Offset Values

X Long Lens Offset: 0

Y Long Lens Offset: 0

- **Settings:** Settings Page.
- **Video Codec Selection:** Video Encoder Selection. Optional codecs are H.264 and H.265 (for video recording).
- **VENC Settings:** Video Encoding Settings.
- **Main VENC Bitrate (Kbps, max 20000):** Streaming Bitrate Setting. Allows configuring and modifying the bitrate of the streaming video, with a range of 0-20000 kbps.
- **VIS VENC Bitrate (Kbps, max 81920):** Visible Light Bitrate Setting. Allows configuring and modifying the bitrate of the visible light video, with a range of 0-81920 kbps.
- **IR VENC Bitrate (Kbps, max 20000):** Thermal Imaging Bitrate Setting. Allows configuring and modifying the bitrate of the thermal imaging video, with a range of 0-20000 kbps.
- **Client Control Settings:** Client Control Settings.
- **Control Port:** Used to set the control port number.

■ Web-based Remote Download of Photos/Videos:

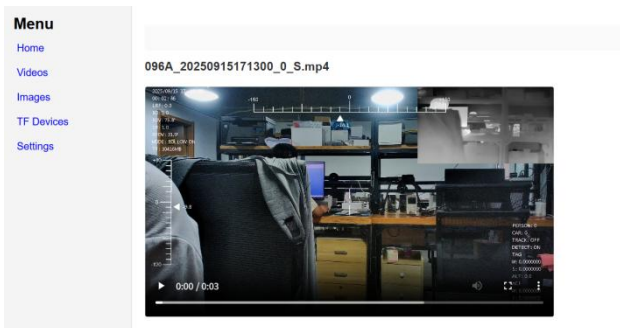
- ① Click Videos or Images to open videos or photos.
- ② When opening photos: Double-click to view.
- ③ When opening recorded videos: Open the video you want to download. Right-click the bottom right corner of the screen to start downloading. Once the browser shows "Download Complete", you can view the recorded video in the saved location.



1.Open the video or photo you want to download.



2.Double-click to open and view the image.



3.Open the video you want to download.

Command Protocol

byte1	byte 2	byte 3	byte 4	byte 5	byte 6	byte 7
Sync byte	Address code	Instruction code1	Instruction code2	Data code1	Data code2	Check code

■ Protocol format:

·Serial port or network port can be used for command control, and the serial port version controller baud rate 115200bps; The network IP address (default) is 192.168.144.119, and the port number is 2000;

·All the values in the protocol are hexadecimal;

·The instruction sync byte is always 0xFF;

·"Address code" is the logical address of the controlled equipment, address range: 0x01-0xFF;

·"Instruction code" indicates different actions;

·"Data codes" 1 and 2 represent the parameters corresponding to the pod command;

·"Check code"= byte 2 + byte 3 + byte 4 + byte 5 + byte 6;

·The "Data receiving protocol" and "S.BUS channel configuration" are only valid on the serial port.

■ Control instruction:

·Motion stop (instruction code 1 is 0x00, instruction code 2 is 0x00)

Example: 0xFF,0x01,0x00,0x00,0x00,0x00,0x01 (Stop all commands in speed control mode)

·Pitch up (instruction code 1 is 0x00, instruction code 2 is 0x08, data code 2 is motion speed, speed range 0x00-0xFF)

Example: 0xFF,0x01,0x00,0x08,0x00,0xFF,0x08 (in upward movement speed 0xFF)

·Pitch down (instruction code 1 is 0x00, instruction code 2 is 0x10, data code 2 is motion speed, speed range 0x00-0xFF)

Example: 0xFF,0x01,0x00,0x10,0x00,0xFF,0x10 (in downward movement speed 0xFF)

·Yaw left (instruction code 1 is 0x00, instruction code 2 is 0x04, data code 1 is motion speed, speed range 0x00-0xFF)

Example: 0xFF,0x01,0x00,0x04,0xFF,0x00,0x04 (to speed 0xFF movement to the left)

·Yaw right (instruction code 1 is 0x00, instruction code 2 is 0x02, data code 1 is motion speed, speed range 0x00-0xFF)

Example: 0xFF,0x01,0x00,0x02,0xFF,0x00,0x02 (to speed 0xFF movement to the right)

·PTZ left and up (instruction code 1 is 0x00, instruction code 2 is 0x0C, data code 1 is left motion speed, data code 2 is up motion speed, speed range 0x00-0xFF)

Example: 0xFF,0x01,0x00,0x0C,0xFF,0xFF,0x0B (in speed 0xFF movement on the left)

·PTZ left and down (instruction code 1 is 0x00, instruction code 2 is 0x14, data code 1 is left motion speed, data code 2 is down motion speed, speed range 0x00-0xFF)

Example: 0xFF,0x01,0x00,0x14,0xFF,0xFF,0x13 (in speed 0xFF movement under the left)

·PTZ right and up (instruction code 1 is 0x00, instruction code 2 is 0x0A, data code 1 is the right movement speed, data code 2 is the up movement speed, speed range 0x00-0xFF)

Example: 0xFF,0x01,0x00,0x0A,0xFF,0xFF,0x09 (to upper right movement with speed 0xFF)

·PTZ right and down (instruction code 1 is 0x00, instruction code 2 is 0x12, data code 1 is the right movement speed, data code 2 is the down movement speed, speed range 0x00-0xFF)

Example: 0xFF,0x01,0x00,0x12,0xFF,0xFF,0x11 (to lower right movement with speed 0xFF)

·Visible light zoom- (instruction code 1 is 0x00, instruction code 2 is 0x20, data code 1 is zoom speed, speed range 0x00-0x08)

Example: 0xFF,0x01,0x00,0x20,0x04,0x00,0x25 (Visible light zooms to the near end at speed 0x04)

·Visible light zoom+ (instruction code 1 is 0x00, instruction code 2 is 0x40, data code 1 is zoom speed, speed range 0x00-0x08)

Example: 0xFF,0x01,0x00,0x40,0x04,0x00,0x45 (Visible light is zoomed out to the far end at speed 0x04)

·Visible light zoom stop (instruction code 1 is 0x00, instruction code 2 is 0x60, data code 1 is 0x00)

Example: 0xFF,0x01,0x00,0x60,0x00,0x00,0x61 (Visible light zoom stop)

·Point to move (screen XY coordinates) (instruction code 1 is 0x10, instruction code 2 is 0x00, data code 1 is X value (↔), data code 2 is Y value (↑), speed range 0x00-0xFF, INYYO 46W does not support this function)

Example: 0xFF,0x01,0x10,0x00,0x40,0x40,0x91 (Point to move to the top-left 1/4 of the screen)

·Pitch angle control (instruction code 1 is 0x10, instruction code 2 is 0x01, (data code 1*256+ data code 2)÷50 are angle values (signed int16))

Example: 0xFF,0x01,0x10,0x01,0x01,0xF4,0x07 (Pitch rotated to 10 degrees)

·Yaw angle control (instruction code 1 is 0x10, instruction code 2 is 0x02, (data code 1*256+ data code 2)÷50 are angle values (signed int16))

Example 1: 0xFF,0x01,0x10,0x02,0x13,0x88,0xAE (Yaw rotation to 100 degrees)

Example 2: 0xFF,0x01,0x10,0x02,0xEE,0x6C,0x6D (Yaw rotation to -90 degrees)

·Point tracking (screen XY coordinates) (instruction code 1 is 0x11, instruction code 2 is 0x00, data code 1 is X value (↔), data code 2 is Y value (↑), speed range 0x00-0FF)

Example 1: 0xFF,0x01,0x11,0x00,0x40,0x40,0x92 (Lock the top left quarter of the screen for tracking)

Example 2: 0xFF,0x01,0x11,0x00,0x7F,0x7F,0x10 (Lock the center of the screen for tracking)

·Stop tracking (instruction code 1 is 0x11, instruction code 2 is 0x01)

Example: 0xFF,0x01,0x11,0x01,0x00,0x00,0x13 (Stop target tracking)

·Open the target detection (instruction code 1 is 0x11, instruction code 2 is 0x02, Only the photoelectric pod with AI detection, identification and tracking function supports this function)

Example: 0xFF,0x01,0x11,0x02,0x00,0x00,0x14 (Open the target detection identification)

·Close the target detection (instruction code 1 is 0x11, instruction code 2 is 0x03, Only the photoelectric pod with AI detection, identification and tracking function supports this function)

Example: 0xFF,0x01,0x11,0x03,0x00,0x00,0x15 (Close the target detection identification)

·Open test aided tracking (instruction code 1 is 0x11, instruction code 2 is 0x04, the auxiliary detection function is to use the detection ability to prevent the loss of the target when the target tracking is blocked, and only the photoelectric pod with AI detection, recognition and tracking function supports this function)

Example: 0xFF,0x01,0x11,0x04,0x00,0x00,0x16 (Open test aided tracking)

·Close test aided tracking (instruction code 1 is 0x11, instruction code 2 is 0x05, only the photoelectric pod with AI detection, recognition and tracking function supports this function)

Example: 0xFF,0x01,0x11,0x05,0x00,0x00,0x17 (Close test aided tracking)

·Take a picture (instruction code 1 is 0x12, instruction code 2 is 0x00)

Example: 0xFF,0x01,0x12,0x00,0x00,0x00,0x13 (Take a picture)

·Start recording (instruction code 1 is 0x12, instruction code 2 is 0x01)

Example: 0xFF,0x01,0x12,0x01,0x00,0x00,0x14 (Start recording)

·Stop recording (instruction code 1 is 0x12, instruction code 2 is 0x02)

Example: 0xFF,0x01,0x12,0x02,0x00,0x00,0x15 (Stop recording)

·Enable follow (instruction code 1 is 0x13, instruction code 2 is 0x00)

Example: 0xFF,0x01,0x13,0x00,0x00,0x00,0x14 (Switch to Enable follow)

·Disable follow (instruction code 1 is 0x13, instruction code 2 is 0x01)

Example: 0xFF,0x01,0x13,0x01,0x00,0x00,0x15 (Switch to Disable follow)

·One-click down (instruction code 1 is 0x13, instruction code 2 is 0x02, used to collect ortho image,

this function is disabled when PTZ is mounted)

Example: 0xFF,0x01,0x13,0x02,0x00,0x00,0x16 (PTZ pitch axis turned to -90°, maintain vertical looking posture)

·One-click reset (instruction code 1 is 0x13, instruction code 2 is 0x03)

Example: 0xFF,0x01,0x13,0x03,0x00,0x00,0x17 (Yaw axis and pitch axis return to the middle position)

·Picture-in-picture mode switching (instruction code 1 is 0x14, instruction code 2 is 0x00, data code 1 is picture mode,0x00: visible light embedded thermal imaging,0x01: thermal imaging embedded visible light,0x02: visible light,0x03: thermal imaging, only the photoelectric pod containing a variety of optical camera modules has this function)

Example: 0xFF,0x01,0x14,0x00,0x02,0x00,0x17 (Switch to visible light)

·Thermal imaging black heat, white heat, color switching (instruction code 1 is 0x15, instruction code 2 is 0x00, data code 1 is black heat, white heat, color switch, 0x00: white heat,0x01: black heat, 0x02: color, only the photoelectric pod containing the thermal imaging module has this function)

Example: 0xFF,0x01,0x15,0x00,0x01,0x00,0x17 (Thermal imaging mode switch to black heat)

·Single ranging/Triggered Location (instruction code 1 is 0x16, instruction code 2 is 0x00, Only optical Pods containing laser ranging modules have this function. (Laser ranging pods can automatically locate targets after entering the specified protocol and ranging at the same time.))

Example: 0xFF,0x01,0x16,0x00,0x00,0x00,0x17 (Distance once and target location)

·Turn on continuous ranging (instruction code 1 is 0x16, instruction code 2 is 0x01, Only the photonics pod containing the laser ranging module has this function)

Example: 0xFF,0x01,0x16,0x01,0x00,0x00,0x18 (Turn on continuous ranging)

·Turn off continuous ranging (instruction code 1 is 0x16, instruction code 2 is 0x02, Only the photonics pod containing the laser ranging module has this function)

Example: 0xFF,0x01,0x16,0x02,0x00,0x00,0x19 (Turn on continuous ranging)

·Thermal imaging electronic zoom (instruction code 1 is 0x17, instruction code 2 is 0x00, data code 1 is electronic zoom multiple (1-8 times), 0x00:1 times,0x01:2 times,0x02:3 times,0x03:4 times, only the photoelectric pod containing the thermal imaging module has this function)

Example: 0xFF,0x01,0x17,0x00,0x01,0x00,0x19 (Thermal imaging zoom to 2X)

·Turn on electronic image stabilization (instruction code 1 is 0x18, instruction code 2 is 0x00, only the photoelectric pod with AI detection, identification and tracking function supports this function)

Example: 0xFF,0x01,0x18,0x00,0x00,0x00,0x19 (Turn on electronic image stabilization)

·Turn off electronic image stabilization (instruction code 1 is 0x18, instruction code 2 is 0x01, only the photoelectric pod with AI detection, identification and tracking function supports this function)

Example: 0xFF,0x01,0x18,0x01,0x00,0x00,0x1A (Turn off electronic image stabilization)

·Turn on OSD (instruction code 1 is 0x19, instruction code 2 is 0x00)

Example: 0xFF,0x01,0x19,0x00,0x00,0x00,0x1A (Open screen OSD information)

·Turn off OSD (instruction code 1 is 0x19, instruction code 2 is 0x01)

Example: 0xFF,0x01,0x19,0x01,0x00,0x00,0x1B (Close screen OSD information)

·Turn on visible light manual focus (instruction code 1 is 0x1D, instruction code 2 is 0x00)

Example: 0xFF,0x01,0x1D,0x00,0x00,0x00,0x1E (Turn on visible light manual focus)

·Turn off visible light manual focus (instruction code 1 is 0x1D, instruction code 2 is 0x01)

Example: 0xFF,0x01,0x1D,0x01,0x00,0x00,0x1F (Turn off visible light manual focus)

·Focus the near end manually (instruction code 1 is 0x1D, instruction code 2 is 0x02)

Example: 0xFF,0x01,0x1D,0x02,0x00,0x00,0x20 (Visible to the remote focusing)

·Focus the distal end manually (instruction code 1 is 0x1D, instruction code 2 is 0x03)

Example: 0xFF,0x01,0x1D,0x03,0x00,0x00,0x21 (Restore default video streaming address)

·Manual focus Stop(instruction code 1 is 0x1D, instruction code 2 is 0x04)

Example: 0xFF,0x01,0x1D,0x04,0x00,0x00,0x22

·Query S.BUS channel configuration (instruction code 1 is 0x1E, instruction code 2 is 0x00, the current S.BUS channel configuration will be returned after sending)

Example: 0xFF,0x01,0x1E,0x00,0x00,0x00,0x1F (Query S.BUS channel configuration)

·Query movement time (instruction code 1 is 0x1E, instruction code 2 is 0x01)

Example: 0xFF,0x01,0x1E,0x01,0x00,0x00,0x20

·Query version (instruction code 1 is 0x1E, instruction code 2 is 0x02.Return data format: EE, 06, 0B, Version type, pod model, date, time, minute, sum check. The date is 3 bytes, and the rest are 1 bytes.)

Example: 0xFF,0x01,0x1E,0x02,0x00,0x00,0x21

·Specifies the return frequency of pod status information (instruction code is 0x20 0x00, data code 1 is the return frequency, 0x01 corresponds to 1Hz, 0x02 corresponds to 2Hz (default), 0x03 corresponds to 3Hz, ... 0x09 corresponds to 9Hz, 0x0A corresponds to 10Hz, and the value ranges from 1 to 10Hz)

Example 1: 0xff,0x01,0x20,0x00,0x02,0x00,0x23(The return frequency of pod status information is 2Hz)

Example 2: 0xff,0x01,0x20,0x00,0x0A,0x00,0x2B(The return frequency of pod status information is

10Hz)

·Restore default video streaming address(instruction code 1 is 0x21, instruction code 2 is 0x00)

Example: 0xFF,0x01,0x21,0x00,0x00,0x00,0x22(Only have AI detection identification tracking function of photoelectric pod to support this feature)

·Query the pull address(instruction code 1 is 0x21, instruction code 2 is 0x01)

Example: 0xFF,0x01,0x21,0x01,0x00,0x00,0x23(Only have AI detection identification tracking function of photoelectric pod to support this feature)

·Turn on PTZ(instruction code 1 is 0x22, instruction code 2 is 0x00)

Example: 0xFF,0x01,0x22,0x00,0x00,0x00,0x23

·Turn off PTZ(instruction code 1 is 0x22, instruction code 2 is 0x01)

Example: 0xFF,0x01,0x22,0x01,0x00,0x00,0x24

·PTZ reboot(instruction code 1 is 0x22, instruction code 2 is 0x02)

Example: 0xFF,0x01,0x22,0x02,0x00,0x00,0x25

·Movement reboot(instruction code 1 is 0x22, instruction code 2 is 0x03)

Example: 0xFF,0x01,0x22,0x03,0x00,0x00,0x26

·Set data reply frequency (instruction code 1 is 0x20, instruction code 2 is 0x00, data code 1 is frequency, support 1-10Hz)

Example: 0xFF,0x01,0x20,0x00,0x0A,0x00,0x2B (Set data reply frequency to 10Hz)

Infrared shutter (instruction code 0x29 0x00) 【A4Pro Customization】

Example: 0xFF,0x01,0x29,0x00,0x00,0x00,0x2A

Infrared Super-resolution Switch (instruction code 0x2A 0x00) 【A4Pro Customization】

Example: 0xFF,0x01,0x2A,0x00,0x01,0x00,0x2C Infrared Super-resolution on

Example: 0xFF,0x01,0x2A,0x00,0x00,0x00,0x2B Infrared Super-resolution off

·The initial movement speed of the in PTZ speed control mode is 0-45 °/s;

·The initial movement speed of the One-click reset/One-click down, angle control, point to move function is about 300 °/s. When approaching the specified angle, the speed will gradually decrease to complete the action;

·The angle control Instruction cannot input the angle value exceeding the working range of the PTZ;

·The default data reply frequency is 2Hz;

·After entering the specified receiving protocol, the photoelectric pod will automatically conduct target positioning.

Response data:

No.	Function	Byte	Note
1	Header	0xEE	
2	Message ID	0x01	
3	Frame length	0x1D	The length of all messages is 29 bytes
4	Laser ranging distance (decimeter)	Low eight	Product data without laser ranging function is 0
5		High eight	
6	PTZ roll angle (@0.1°)	Low eight	Tilting left is negative, tilting right is positive
7		High eight	
8	PTZ pitch angle (@0.1°)	Low eight	Head down is negative, head up is positive
9		High eight	
10	PTZ yaw angle (@0.1°)	Low eight	Turn right from 0 to 180
11		High eight	Turn left from 0 to -180
12	Visible light zoom multiple (integer)		
13	Track status		0x00: Not tracked 0x01: Tracking
14	Target latitude*10000000	Low byte	Example: The actual latitude is 38.1234567, and the four byte data is 381234567
15			
16			
17		High byte	
18	longitude*10000000	Low byte	Example: The actual longitude is 114.1234567, and the data of these four bytes is 1141234567
19			
20			
21		High byte	
22	Target height (decimeter)	Low eight	
23		High eight	
24	Visible light zoom multiple (0.1x)	Low eight	
25		High eight	
26	Reserve		

27	Reserve		
28	PTZ working mode		0x00: Enable follow, 0x01: Disable follow, 0x02: One-click down
29	Sum check		1-28 bytes sum, take the lower eight bits

·Example:0xEE,0x01,0x1D,0xB8,0x0B,0x32,0x00,0x3E,0xFE,0xE8,0x03,0x05,0x01,0x87,0x2D,0xB9,0x16,0x87,0xDB,0x05,0x44,0x7B,0x00,0x00,0x00,0x00,0x00,0x01,0xD8

(Laser ranging is 300m, roll angle is 5°, pitch angle is -45°, yaw angle is 100°, visible light zoom is 5x, tracking is underway, target latitude is 38.1234567, target longitude is 114.1234567, target altitude is 12.3m, and PTZ working mode is disable follow.)

■ Data receiving protocol:

No.	Function	Byte	Note
1	Header	0xEE	
2	Message ID	0x81	
3	Frame length	0x22	The length of all messages is 34 bytes
4	Aircraft (mechanical platforms) roll angle (@0.1°)	Low eight	Tilting left is negative, tilting right is positive
5		High eight	
6	Aircraft (mechanical platforms) pitch angle (@0.1°)	Low eight	Head down is negative, head up is positive
7		High eight	
8	Aircraft (mechanical platforms) yaw angle (@0.1°)	Low eight	Turn right from 0 to 180 Turn left from 0 to -180
9		High eight	
10	Aircraft (mechanical platforms) latitude*10000000	Low byte	Example: The actual latitude is 38.1234567, and the four byte data is 381234567
11			
12			
13		High byte	

14	Aircraft (mechanical platforms) longitude*10000000	Low byte	Example: The actual longitude is 114.1234567, and the data of these four bytes is 1141234567
15			
16			
17		High byte	
18	Aircraft (mechanical platforms) altitude (decimeter)	Low eight	
19		High eight	
20	Aircraft (mechanical platforms) relative height (decimeter)	Low eight	
21		High eight	
22	GPS time (Beijing time)	Year	Example: This byte will be 21 in 2021
23		Month	
24		Day	
25		Hour	24-hour
26		Minute	
27		Second	
28	Aircraft (mechanical platforms) eastward speed(cm/s)	Low eight	East direction is positive
29		High eight	
30	Aircraft (mechanical platforms) northbound speed(cm/s)	Low eight	North direction is positive
31		High eight	
32	Aircraft (mechanical platforms) ascent speed(cm/s)	Low eight	Sky direction is positive
33		High eight	
34	Sum check		1-33 bytes sum, take the lower eight bits

·Example:

0xEE,0x81,0x22,0x32,0x00,0x3E,0xFE,0xE8,0x03,0x87,0x2D,0xB9,0x16,0x87,0xDB,0x05,0x44,0
xD0,0x07,0x7B,0x00,0x00,0x00,0x00,0x00,0x00,0x00,0x00,0x00,0x00,0x00,0x00,0x00,0x6A

(The aircraft (mechanical platforms) roll angle is 5°, pitch angle is -45°, yaw angle is 100°, latitude is 38.1234567, longitude is 114.1234567, altitude is 200, relative height is 12.3)

■ Current S.BUS channel configuration reply:

No.	Function	Byte	Note
1	Header	0xEE	
2	Message ID	0x04	
3	Frame length	0x1C	The length of all messages is 28 bytes
4	Pitch		The corresponding byte for each function represents the corresponding channel number, such as the pitch byte is 0x01, and the yaw byte is 0x03, which represent channel 1 controlling pitch and channel 3 controlling yaw. The channel number range is 1-16. If it exceeds the range, it cannot be set successfully, and "0" represents not activating this function.
5	Yaw		
6	Visible light zoom		
7	Visible light manual focus		
8	PTZ Mode switch, One-click down		
9	One-click reset		
10	Photography		
11	Target detection and tracking		
12	PIP, black heat, white heat, color		
13	Thermography electronic zoom		
14	Laser ranging(none)		
15	Laser night vision (none)		
16	OSD-switch		
17	Reserve		
18	Reserve		
19	Reserve		
20	Reserve		

21	Reserve		
22	Reserve		
23	Reserve		
24	Reserve		
25	Reserve		
26	Reserve		
27	Reserve		
28	Sum check		1-27 byte sum, take the lower eight bits

- Example:

```
0xEE,0x04,0x1C,0x01,0x03,0x02,0x04,0x05,0x06,0x00,0x00,0x00,0x00,0x00,0x00,
0x00,0x00,0x00,0x00,0x00,0x00,0x00,0x00,0x00,0x00,0x00,0x23
```

(Pitch is CH1, yaw is CH3, zoom is CH2, manual focus is CH4, mode switch is CH5, one click reset is CH6, and other functions are not mapped)

The instructions for setting the S.BUS channel can be found in "S.BUS Channel Settings" in this article.

After Sales Service

This chapter mainly introduces the after-sales service and the relevant statements of the scope of non-after-sales protection.

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After Sales Service

After Sales Service

·General Terms of Service: This after-sales service only applies to the terminal products purchased by you for your own use and not for resale. Users should carefully follow the instructions in the product manual to use the products and follow the service procedures of the distributor.

·Product warranty period: Please confirm the specific warranty period with the dealer before purchasing this product. The warranty period of this product starts from the day after you receive the goods, and valid proof of purchase, bills, invoices and order numbers must be provided.

·Warranty parts: Pod shell, power control module, buck module, lens equipment, quick-release bracket (excluding wire); Other accessories in addition to the above parts are not covered by the warranty.

·Application for after-sales service: During the warranty period, if the product can not achieve the guaranteed function, please contact the relevant service personnel of the dealer, and explain the problem of the product in detail, in order to obtain the corresponding after-sales service; If you cannot solve your problem through telephone or remote video communication, you need to contact logistics to send the product to the designated address according to the dealer's designated service personnel for further testing, and the dealer will arrange service according to the type of warranty service enjoyed by the product;

The application for product repair requires a guarantee that the distributor or manufacturer has full, free and safe access to your equipment to provide after-sales service, and that the product or part is free from any legal restrictions preventing its replacement; If the product or part is not owned by you, obtain a license from the owner of the product or part so that the distributor or manufacturer can provide you with after-sales service.

·Replacement of products and parts: If your warranty service involves replacement of products or parts, the replaced products or parts will become the property of the distributor or manufacturer, and the replaced products or parts will become your property, and only the original parts of the product can be replaced without modification; The replacement product or part provided by the after-sales service may not be new, but it can be guaranteed that the updated part can be in good working condition and at least equal in performance to the replaced part, and the replaced product or part enjoys the same warranty service during the remaining warranty period of the original product.

·The delivery fee shall be confirmed with the distributor in advance, and the cost of sending to the company shall be borne by the customer.

·Do not disassemble or repair yourself, otherwise you will not be able to enjoy the product warranty service.

·All final interpretation rights belong to the product developer.



Please take good care of all the purchase documents and relevant electronic documents of this product.

Scope Of Non-After-Sales Guarantee

- Device wear, fragmentation, burning and other accidents caused by man-made non product quality problems.
- Damage caused by unauthorized modification, disassembly and shell opening under the guidance of unofficial instructions.
- Damage caused by improper installation, use and operation not in accordance with the instructions in the product manual.
- Repair damage caused by assembly parts by yourself.
- Damage caused by circuit modification guided by unofficial instructions, or improper use of battery packs and chargers.
- Damage caused by handling in extremely harsh environments, such as wind, rain, dust, etc.
- Damage caused by manipulation in a complex electromagnetic environment or strong interference source environment, such as mining areas, towers, high-voltage lines, substations, etc.
- Damage caused by mutual interference with other wireless devices, such as transmitter, signal transmission, WiFi signal interference.
- Damage caused by forced operation when parts are aged or damaged.
- Damage caused by reliability and compatibility issues when used with third-party components that are not certified by developers and manufacturers.
- Damage caused by insufficient discharge when the power supply is insufficient, or the voltage is too high, or when the battery with defective quality is used.
- Uninterrupted or faulty operation of the product.
- Continuous or wrong operation of the product.
- Failure or damage caused by any third party product (including all other products supplied by the distributor/manufacturer or integrated into the Product at your request).
- Change or tear off the identification label and damage the anti tear sticker.
- Unable to provide valid purchase vouchers or forge, alter behavior.

·Force majeure caused by local policies, natural disasters or other special reasons will not be able to provide after-sales service.



Please take good care of all the purchase documents and relevant electronic documents of this product.

Thank you for your use

This product is approved to leave factory as it meets the manufacturer's standard after inspection.

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